



# Dialogic<sup>®</sup> Audio Conferencing API

Programming Guide

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*December 2007*

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# Revision History

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This revision history summarizes the changes made in each published version of this document.

Document No.	Publication Date	Description of Revisions
05-1920-005	December 2007	<p>Made global changes to reflect Dialogic brand and changed title to “Dialogic® Audio Conferencing API Programming Guide.”</p> <p>Combined Windows and Linux versions of this document so that this version supports both operating systems, and supersedes “Dialogic® Audio Conferencing API Programming Guide” (document number 05-1879-005).</p> <p><a href="#">Building Applications</a> chapter: Added note in <a href="#">Required Libraries</a> section about listing Dialogic® libraries before all other libraries.</p>
05-1920-004	April 2006	<p>This document version was released in conjunction with SR 6.1 Windows for CompactPCI GA.</p> <p><a href="#">Product Description</a> chapter: Made minor changes to the active talker and volume control features.</p> <p><a href="#">Programming Models</a> chapter: Added new information for <a href="#">Multithreaded Programming</a> (IPY00010015 = PTR 34415).</p> <p><a href="#">Application Development Guidelines</a> chapter: Added new information for <a href="#">DTMF Detection Considerations</a> (IPY00007758 = PTR 31134).</p> <p>In <a href="#">Initialization of Dialogic® DM3 Board Parameters</a> section, changed the description of the MSG_ACTID parameter to indicate that it enables/disables active talker identification (or notification) and not the active talker feature itself (IPY00006584 = PTR 36199 and IPY00010946 = PTR 36323).</p> <p><a href="#">Active Talker</a> chapter: Changed the description of the MSG_ACTID parameter to indicate that it enables/disables active talker identification (or notification) and not the active talker feature itself (IPY00006584 = PTR 36199 and IPY00010946 = PTR 36323).</p> <p><a href="#">Volume Control</a> chapter: Added information on direct application control of output volume (per party), and reworded information for user control of volume by pre-programmed DTMF (per board).</p> <p>Added information on how to configure input volume automatic gain control parameters.</p> <p>Added description of how to do input volume muting.</p> <p><a href="#">Background Music</a> chapter: Changed description of how to implement background music in an application so that it doesn't refer to MSG_ACTID (IPY00006584 = PTR 36199 and IPY00010946 = PTR 36323).</p>

## Revision History

Document No.	Publication Date	Description of Revisions
05-1920-003	May 2005	<p><b>Product Description</b> chapter: Described the active talker feature more accurately (PTR 34210). Described the tone clamping feature more accurately (PTR 34672).</p> <p><b>Initialization of Dialogic® DM3 Board Parameters</b> section: Described the active talker parameters more accurately (PTR 34210), including stating that by default it is enabled for DM3 architecture boards, removing the MSG_ALGORITHM parameter (PTR 34382), which does not apply to DM3, and clarifying the MSG_ACTTALKERNOTIFYINTERVAL parameter, providing default value, units, etc. Also, clarified the MSG_TONECLAMP parameter (PTR 34672).</p> <p><b>Resource Allocation</b> section: Clarified description and added details on maximum conference size, maximum number of conference resources, and conference bridging.</p> <p><b>Conference Bridging</b> chapter: Added details on maximum conference size and maximum number of conference resources.</p> <p><b>Active Talker</b> chapter: Described active talker implementation more accurately, correcting errors and adding details (PTR 34210).</p> <p><b>Background Music</b> chapter: Added new chapter describing how to implement background music in an application, such as a dating chat line application where two callers talk while music plays in the background.</p>
05-1920-002	August 2004	<p><b>Error Handling</b> chapter: Updated description of system error handling (PTR 28014).</p> <p><b>Conference Bridging Limitations</b> section: Removed incorrect limitation that master conference and conferences bridged to it must be on separate DCB devices, and replaced with description how to do it (PTR 29144).</p>
05-1920-001	November 2002	Initial version of document. Much of the information contained in this document was previously published in the <i>Dialogic Audio Conferencing Software Reference for Windows</i> , document number 05-0512-002.

# About This Publication

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The following topics provide information about this publication:

- [Purpose](#)
- [Applicability](#)
- [Intended Audience](#)
- [How to Use This Publication](#)
- [Related Information](#)

## Purpose

This publication provides guidelines for building computer telephony applications using the Dialogic<sup>®</sup> Audio Conferencing API.

This publication is a companion guide to the *Dialogic<sup>®</sup> Audio Conferencing API Library Reference* that provides details on functions and parameters in the audio conferencing library.

## Applicability

This document version (05-1920-005) is published for Dialogic<sup>®</sup> Host Media Processing Software Release 3.0WIN.

This document may also be applicable to other software releases (including service updates) on Linux or Windows<sup>®</sup> operating systems. Check the Release Guide for your software release to determine whether this document is supported.

## Intended Audience

This publication is written for the following audience:

- Distributors
- System Integrators
- Toolkit Developers
- Independent Software Vendors (ISVs)
- Value Added Resellers (VARs)
- Original Equipment Manufacturers (OEMs)

## How to Use This Publication

Refer to this publication after you have installed the hardware and the system software which includes the audio conferencing library.

This publication assumes that you are familiar with the Linux and Windows<sup>®</sup> operating systems, as well as the C programming language.

The information in this guide is organized as follows:

- [Chapter 1, “Product Description”](#) introduces the key features of the audio conferencing library and provides a brief description of each feature.
- [Chapter 2, “Programming Models”](#) provides a brief overview of supported programming models.
- [Chapter 3, “Device Handling”](#) discusses topics related to devices, such as device naming concepts and how to open/close devices.
- [Chapter 4, “Event Handling”](#) provides information about functions used to handle events.
- [Chapter 5, “Error Handling”](#) provides information about handling errors in your application.
- [Chapter 6, “Application Development Guidelines”](#) provides guidelines for developing applications with the audio conferencing library.
- [Chapter 7, “Active Talker”](#) provides details about the active talker feature.
- [Chapter 8, “Conference Bridging”](#) discusses how to connect conferences together via a conference bridge.
- [Chapter 9, “Volume Control”](#) explains how to enable volume control for conferees.
- [Chapter 10, “Background Music”](#) explains how to implement background music, such as for a dating chat line where two callers talk while music plays in the background.
- [Chapter 11, “Building Applications”](#) discusses compiling and linking requirements such as include files and library files.

## Related Information

See the following for additional information:

- <http://www.dialogic.com/manuals/> (for Dialogic<sup>®</sup> product documentation)
- <http://www.dialogic.com/support/> (for Dialogic technical support)
- <http://www.dialogic.com/> (for Dialogic<sup>®</sup> product information)

This chapter provides information about the features available in the Dialogic® Audio Conferencing API library.

Audio conferencing is software that supports development of host-based audio conferencing applications on Dialogic® DM3 architecture boards.

**Note:** In order to enable audio conferencing on a Dialogic® board, you must configure the board with a Media Load that supports conferencing resources. For complete information about Media Loads, refer to the Configuration Guide associated with your release.

Key features of the Dialogic® Audio Conferencing Software include:

- Bridging multiple conferences together so that all conferees in two or more established conferences can speak with and/or listen to one another.
- Coach/pupil feature allows two selected conferees to establish a private communication link with respect to the overall conference. The coach is a private member of the conference and is only heard by the pupil. However, the pupil cannot speak privately with the coach.
- DTMF digit detection for any conferee, allowing the application to determine when or if any party has generated a DTMF digit.
  - Note:** Any conferee in receive-only mode cannot generate DTMF digits within the conference, therefore any digits dialed by a conferee in receive-only mode will not generate DCBEV\_DIGIT events.
- Volume control for any conferee.
- DTMF tone clamping that reduces the amount of DTMF tones heard during a conference. tone clamping applies to the transmitted audio going into the conference and does not affect DTMF function. It can be enabled on a per-party basis or for all conferees on a board.
  - Note:** Even with tone clamping, DTMF tones may be heard by conferees if the application encourages the user to repeatedly press DTMF tones; for example, press 9 to raise volume.
- Automatic Gain Control (AGC) for all conferees. AGC is an algorithm for normalizing an input signal to a target level. The AGC algorithm discriminates between voiced and unvoiced signals within a conference.
- By default, the active talker feature sums the 3 most active talkers in a conference, so that the conversation doesn't get drowned out when too many people talk at once. The active talker feature also provides data on active talkers through the `dcb_gettalkers()` and `dcb_GetAtiBitsEx()` functions. Active talkers are determined by their loudness; i.e., the strength of their "non-silence" energy. The active talker feature is enabled by default.
- Monitoring feature enabling many participants to monitor a single conference without interrupting the conference.
- Echo cancellation for each talker.

## ***Product Description***

This chapter briefly discusses the Dialogic® Standard Runtime Library and supported programming models. The following topics are discussed:

- Dialogic® Standard Runtime Library ..... 15
- Asynchronous Programming Model ..... 15
- Synchronous Programming Model ..... 15
- Multithreaded Programming ..... 16

## 2.1 Dialogic® Standard Runtime Library

The Dialogic® Standard Runtime Library provides a set of common system functions that are device independent. The Dialogic® Standard Runtime Library consists of a data structure, event management functions and device management functions (called standard attribute functions). You can use the library to simplify application development, such as by writing common event handlers to be used by all devices (conferencing, voice, network etc.).

When developing audio conferencing applications, refer to the Standard Runtime Library documentation in tandem with the audio conferencing library documentation. For more information about the Dialogic® Standard Runtime Library, see the *Dialogic® Standard Runtime Library API Library Reference* and the *Dialogic® Standard Runtime Library API Programming Guide*.

## 2.2 Asynchronous Programming Model

Asynchronous programming enables a single program to control multiple conferencing devices within a single process. This allows the development of complex applications where multiple tasks must be coordinated simultaneously.

For more information about asynchronous programming models, see the *Dialogic® Standard Runtime Library API Library Reference*.

## 2.3 Synchronous Programming Model

The synchronous programming model uses functions that block application execution until the function completes. This model requires that each conferencing device be controlled from a separate process. This allows you to assign distinct applications to different channels dynamically in real time.

## **Programming Models**

For more information about asynchronous programming models, see the *Dialogic® Standard Runtime Library API Library Reference*.

## **2.4 Multithreaded Programming**

The Dialogic® DCB Audio Conferencing API supports multithreaded programming where one thread is designed to handle one conference. Applications must be designed to handle one or more conferences per thread or one or more boards per thread and not concurrently access the same conference or board handles from multiple threads. If this rule is violated, unpredictable results or faults may occur.



This chapter discusses the following topics related to device handling on physical boards:.

- [Concepts](#) ..... 17
- [Device Names](#) ..... 17
- [Opening and Using Devices](#) ..... 19

## 3.1 Concepts

The concepts discussed in this section are helpful in understanding devices and device handling.

device

A device is a computer peripheral or component controlled through a software device driver. A resource board, such as a voice resource, conferencing resource, and network interface board contain one or more logical board devices. Each digital signal processor (DSP) or time slot on the board is considered a device. The Dialogic® Audio Conferencing API distinguishes between a board device and a DSP device.

device name

A device name is a literal reference to a device, used to gain access to the device via an **xx\_open()** function, where “xx” is the prefix defining the type of device to be opened. The “xx” prefix refers to “dcb” for conferencing device, “dti” for network interface device, “dxxx” for voice device and so on.

device handle

A device handle is a numerical reference to a device, obtained when a device is opened using **xx\_open()**, where “xx” is the prefix defining the device to be opened. The “xx” prefix refers to “dcb” for conferencing device, “dti” for network interface device, “dxxx” for voice device and so on. The device handle is used for all operations on that device.

## 3.2 Device Names

The system software assigns device names in a process described in the following topics:

- [Overview of Device Names](#)
- [Designating Device Types](#)
- [Device Naming Rule](#)
- [Rules for Dialogic® DM3 Architecture Boards](#)

### 3.2.1 Overview of Device Names

The system software creates standard device names for conferencing boards and DSPs that reside on conferencing boards. These names are input as the **name** parameter to, for example, the

**dcb\_open()** function, which return the device handles necessary for many essential API calls, such as **dcb\_addtoconf()** and **dcb\_getbrdparm()**.

### 3.2.2 Designating Device Types

The system software designates devices as the following types:

- **Audio conferencing.** Device names for this type receive the prefix **dcb**.
- **Digital network interface.** Device names for this type receive the prefix **dti**.
- **Voice.** Device names for this type receive the prefix **dxxx**.

For more information on device types for each technology, see the appropriate documentation, such as the Dialogic® Digital Network Interface API and Dialogic® Voice API documentation sets.

### 3.2.3 Device Naming Rule

A device name is assigned to each conference device or each component in a board as follows:

#### **dcbBn**

where **n** is the device number assigned in sequential order down the list of sorted conference boards.

A conference device name can be appended with a DSP identifier:

#### **dcbBnDy**

where **y** corresponds to one of the board's DSPs. Examples of DSP device names for conferencing boards are **dcbB1D1** and **dcbB1D2**. Individual conferences are associated with DSPs and may not span DSPs. Each conferencing board DSP has a certain number of conferencing resources, depending on the board model and the Media Load that is used to configure the board. Refer to the Configuration Guide associated with your release for information about the number of conference resources supported by Dialogic® DM3 boards. Every time a conferee or a conference bridge is added to a conference, a conference resource is used. When a conferee is removed from a conference and/or a conference bridge is deleted, the associated resource is freed. If an entire conference is deleted, all associated resources are freed. Refer to [Section 6.4, "Resource Allocation"](#), on page 27 for more information about conferencing resource usage.

### 3.2.4 Rules for Dialogic® DM3 Architecture Boards

When using the Dialogic® Audio Conferencing API, the following rules apply specifically to Dialogic® DM3 board naming and numbering:

- A single physical Dialogic® DM3 board device can contain multiple virtual boards that are each numbered in sequential order; for example, a Dialogic® DM/V960A-4T1 board with four digital network interfaces contains four virtual network interface boards that would follow a sequential numbering pattern such as dtiB1, dtiB2, dtiB3, dtiB4.
- All Dialogic® DM3 board devices are numbered in sequential order based on the logical ID assigned by the DM3 driver: the board having the lowest logical ID will be assigned the next board number, and so on.

### 3.3 Opening and Using Devices

When you open a file, it returns a unique file descriptor for that file. The following is an example of a file descriptor:

```
int file_descriptor;
file_descriptor = open(filename, mode);
```

Any subsequent action you wish to perform on that file is accomplished by identifying the file using **file\_descriptor**. No action can be performed on the file until it is first opened.

Conferencing boards and DSPs work in a similar manner. You must first open a conference device using **dcb\_open( )** before you can perform any operation on it.

When you open a board or DSP device connected to the time division multiplexing (TDM) bus using **dcb\_open( )**, the value returned is a unique device handle for that particular open process. Typically, the device handle is referred to as **devh**:

```
int dspdevh; /*indicates device handler for DSP device*/
dspdevh = dcb_open("dcbBnDy", 0)
```

The DSP device name is **dcbBnDy**, where B is followed by the board number and D is followed by the number of the DSP. An example is dcbB1D2 for board 1, DSP 2.

The device handle for a digital network interface device is referred to as **dtih** (see the *Dialogic® Digital Network Interface Software Reference* for details):

```
int dtih;
dtih = dt_open(dtiBxTx,mode)
```

The device name is **dtiBxTx**, where B is followed by the unique board number and T is followed by the number of the time slot (digital channel), 1 to 24 for T-1 or 1 to 30 for E-1.

For more information on device naming, see [Section 3.2, “Device Names”](#), on page 17.

To use an audio conferencing library function on a DSP, you must identify the DSP with its DSP device handle, **devh**. The DSP device name is used only when opening a DSP device, and all actions after opening must use the handle **devh**.

Board devices are opened by following the same procedure, where **devh** refers to the board device handle.

**Note:** Boards and DSPs are considered separate devices. It is possible to open and use a DSP without ever opening the board it is on. There is no board-DSP hierarchy imposed by the driver.

In applications that spawn child processes from a parent process, device handles are not inheritable from the parent process to the child process. Make sure that devices are opened in the child process.

The system software provides libraries of C language functions that enable you to control the boards and DSPs. For details on opening and closing channels and boards, refer to the function reference descriptions for:

- **dt\_open( )** and **dt\_close( )** in the *Dialogic® Digital Network Interface Software Reference*

## ***Device Handling***

- **dcb\_open()** and **dcb\_close()** in the *Dialogic® Audio Conferencing API Library Reference*

This chapter provides information on functions used to retrieve and handle events that are generated by the functions in the audio conferencing library. Topics include:

- [Overview of Event Handling](#) . . . . . 21
- [Event Management Functions](#) . . . . . 21

## 4.1 Overview of Event Handling

An event indicates that a specific activity has occurred in a conference. The conferencing board's device driver reports activity to the application in the form of events, which allows the program to identify and respond to a specific occurrence in a conference. Events provide feedback on the progress and completion of functions and indicate the occurrence of other conference activities. audio conference library events are defined in the *dclib.h* header file.

For a list of events that may be returned by the audio conferencing software, see the *Dialogic® Audio Conferencing API Library Reference*.

## 4.2 Event Management Functions

Event management functions are used to retrieve and handle events being sent to the application from the firmware. These functions are contained in the Dialogic® Standard Runtime Library and defined in *srllib.h*. The library provides a set of common system functions that are device independent and are applicable to all devices. For more information on event management and event handling, see the *Dialogic® Standard Runtime Library API Programming Guide*.

To enable an event handler for a specified event, follow these steps:

1. Call `sr_enbhdr()`. This function specifies the event and the application defined event handler that is called from a signal handler.
2. Call `dcb_setdigitmsk()` or `dcb_evtstatus()` functions. These functions set the digit message mask.

**Note:** The request for an event to be posted to an event handler must be specified using both the `sr_enbhdr()` and either the `dcb_setdigitmsk()` or `dcb_evtstatus()` functions.

Each of the Event Management functions applicable to conference devices are listed in the following tables. **Table 1** lists values that are required by event management functions. **Table 2** lists values that are returned for event management functions that are used with conferencing devices.

## Event Handling

**Table 1. Conference Device Inputs for Event Management Functions**

Event Management Function	Conference Device specific Input	Value
sr_enbhdr( ) Enable event handler	evt_type	DCBEV_CTU DCBEV_DIGIT
sr_dishdr( ) Disable event handler	evt_type	DCBEV_CTU DCBEV_DIGIT.
sr_waitevt( ) Wait for next event		N/A
sr_waitevtEx( ) Wait for next event		N/A

**Table 2. Conference Device Returns from Event Management Functions**

Event Management Function	Conference Device specific Input	Value
sr_getevtdev( ) Get device handle	device	Conference device handle.
sr_getevttype( ) Get event type	event type	DCBEV_DIGIT DCBEV_CTU
sr_getevtlen( ) Get event length	event length	Number of bytes in the data returned.
sr_getevtdatap( ) Get pointer to event data	event data	Pointer to DCB_DIGITS structure for DCBEV_DIGIT. Pointer to DCB_CT structure, the updated resource table for DCBEV_CTU.

This chapter discusses how to handle errors that can occur when running an audio conferencing application.

All the audio conferencing library functions return a value that indicates the success or failure of the function call. Audio conferencing functions return one of the following values:

- 0  
function success
- 1  
function error

Any call to a library function should therefore check for a return value indicating an error. This can be done using a format similar to the following:

```
/* call to Audio Conferencing library function */  
  
if (dcb_XXX(arguments) == -1) {  
    /* error handling routine */  
}  
/* successful function call -  
   continue processing ... */
```

Using this technique ensures that all errors resulting from a library call will be trapped and handled properly by the application.

If an audio conferencing library function fails, call the Dialogic® Standard Runtime Library standard attribute functions **ATDV\_LASTERR()** and **ATDV\_ERRMSGP()** to determine the reason for failure. For more information about these functions, see the *Dialogic® Standard Runtime Library API Library Reference*.

- Notes:**
1. The **dcb\_open()** and **dcb\_close()** functions are an exception to the error-handling rules. If either of these functions fail, the return code is -1 and it indicates a system error. For Windows®, use the **dx\_fileerrno()** function to obtain the system error value.
  2. If **ATDV\_LASTERR()** returns the **EDT\_SYSTEM** or **E\_MSSYSTEM** error code, an operating system error has occurred. For Windows®, use the **dx\_fileerrno()** function to obtain the system error value.

For a list of errors that can be returned by an audio conferencing library function, see the *Dialogic® Audio Conferencing API Library Reference*.

## ***Error Handling***



This chapter provides programming guidelines and techniques for developing an application using the Dialogic® Audio Conferencing API library. The following topics are discussed:

- Using Symbolic Defines ..... 25
- Initialization of Dialogic® DM3 Board Parameters ..... 25
- Terminating ..... 26
- Resource Allocation ..... 27
- DTMF Detection Considerations. .... 27

## 6.1 Using Symbolic Defines

The system software does not guarantee the numerical values of defines will remain the same as new versions of the software package are released. In general, do not use a numerical value in your application when an equivalent symbolic define is available. Symbolic defines are found in the *dclib.h*, *dtlib.h*, *msilib.h* and *srlib.h* files.

## 6.2 Initialization of Dialogic® DM3 Board Parameters

As a first step, an audio conferencing application must initialize board-level parameters. Use **dcb\_setbrdparm()** to set the board-level parameters. Specific settings for boards that use Dialogic® DM3 architecture include:

**Note:** In a conferencing application, you must open the initial **dcb** device in your system using **dcb\_open()**, call the **dcb\_setbrdparm()** function for the opened device and then close the device using **dcb\_close()**. You can then follow the same sequence for the second **dcb** device, the third **dcb** device and so on. Refer to [Chapter 3, “Device Handling”](#) for more information about **dcb** devices.

### MSG\_ACTID (Active Talker Identification)

Enables or disables Active Talker Identification (or Notification). Possible values are ACTID\_ON or ACTID\_OFF. ACTID\_ON is the default. This parameter does not enable or disable the active talker *feature*, which is always enabled. It only disables the *notification* to the application program. By default, the active talker *feature* sums the 3 most active talkers in a conference, so that the conversation doesn't get drowned out when too many people talk at once. Active talker *notification* provides data on active talkers through the **dcb\_gettalkers()** and **dcb\_GetAtiBitsEx()** functions, which can be used by an application program to identify active talkers; for example, to provide a visual display highlighting the active talkers in a

## Application Development Guidelines

conference. Active talkers are determined by their loudness; i.e., the strength of their “non-silence” energy.

**Note:** In some cases, it is desirable to inactivate the active talker feature, such as for a background music application program. Although you cannot directly disable the active talker *feature*, you can set the noise level threshold by which signals are recognized as either speech or noise. For more information on implementing background music, see [Chapter 10, “Background Music”](#).

### MSG\_ACTTALKERNOTIFYINTERVAL (Active Talker Notification Interval)

Changes the interval specifying how frequently the Active Talker status is updated. The value is specified in 10 ms units. The default value is 100 (in 10 ms units), which results in a 1-second interval, and the maximum value is 1000, which results in a 10-second interval.

**Note:** If a low value is used, it can affect system performance due to the more frequent updating of the status (which results in a high quantity of internal notification messages). If a high value is used, it will result in less frequent updating of status, but the non-silence energy of a conferee may not be reported if it occurs between notification updates. For example, if the notification interval is set to 2 seconds and a conferee only says “yes” or “no” quickly in between notifications, that vocalization by the conferee will not be reported.

### MSG\_TONECLAMP (Tone Clamp Activation)

Enables tone clamping for all parties to reduce the amount of DTMF tones heard in a conference. Tone clamping applies to the transmitted audio going into the conference and does not affect DTMF function. It is meaningful only in the full duplex or the transmit-only mode. Possible values are TONECLAMP\_ON or TONECLAMP\_OFF. TONECLAMP\_OFF is the default. (To enable on a per-party basis, set the MSPA\_PARTY\_TONECLAMP attribute in the MS\_CDT structure for the party.) Even with tone clamping, DTMF tones may be heard by conferees if the application encourages the user to repeatedly press DTMF tones; for example, press 9 to raise volume.

### MSG\_VOLDIG (Volume Control Digits)

Defines the volume control status and volume up/down/reset digits as defined in the MS\_VOL data structure.

If conference resource table updates are desired by the application, use the `dc_b_evtstatus()` to enable event generation.

## 6.3 Terminating

When your process completes, devices should be shut down in an orderly fashion. Tasks that are performed to terminate an application generally include:

- Disabling events
- Stop listening to time slots
- Deleting all conferences
- Closing devices

**Note:** Dialogic® Standard Runtime Library event management functions (such as `sr_dishdlr()`, which disables an event handler) must be called before closing the device that is sending the handler event notifications. See [Chapter 4, “Event Handling”](#) for more information about handling events.

## 6.4 Resource Allocation

The available conference resource count for a specified DSP is retrieved using the **dcb\_dsprescount( )** function.

**Note:** The total number of conference resources, as well as other conference resource limitations if any exist (such as the maximum conference size), depends upon either your particular board and its media load or the resource configuration of your Dialogic® Host Media Processing (HMP) software license. For specific conferencing resource information applicable to a particular board and its media load, see the Configuration Guide associated with your release.

To expand a conference beyond the maximum size allowed by your particular configuration, create a second (master) conference and then connect the two conferences via a conference bridge.

Calling any of the following functions will cause the available resource count to change:

**dcb\_addtoconf( )**

uses one resource every time a conferee is successfully added to a conference

**dcb\_CreateBridge( )**

uses two resources for each bridge: one in the master conference and one in the conference that is bridged to the master conference.

**dcb\_DeleteAllConferences( )**

frees all of a conference board's resources

**dcb\_delconf( )**

frees all resources in use by the conference, including the monitor

**dcb\_DeleteBridge( )**

frees all resources used by the conference bridge

**dcb\_estconf( )**

uses the number of resources as specified by the **numpty** parameter

**dcb\_monconf( )**

uses one resource

**dcb\_remfromconf( )**

frees one resource

**dcb\_unmonconf( )**

frees one resource

**Note:** Resources are not released by a board's firmware if the conferencing application is not properly shut down (for example, an error condition abnormally terminates the application without deleting individual conferences and/or closing individual channels). In this case, you must either design your application to recover and manage the existing conferences or call the **dcb\_DeleteAllConferences( )** function to release all conferencing resources.

## 6.5 DTMF Detection Considerations

DTMF detection is done separately on voice and DCB conferencing libraries.

## ***Application Development Guidelines***

If a DTMF detection is enabled for a conferee, via **dcb\_setdigitmsk()**, and the same receive timeslot is routed to a voice device in listen mode, both devices will detect the tone. Due to the difference in how both libraries detect the tone, it's possible to see the DTMF detected at different times. The DCB library will most likely detect the tone first since it uses the rising edge of the tone for detection.

The application should be aware of the timing difference and take the appropriate actions to avoid timing issues with DTMF detection between both libraries.

For instance, it was observed that for DTMF digits that are long enough, a voice device would still detect a DTMF even if routing of the voice in listen mode was done *after* the DCB already detected the tone (DCBEV\_DIGIT), as substantial DTMF audio was remnant by the time the voice device started listening.

This chapter provides information about the active talker feature.

Active talkers are those conferees providing “non-silence” energy and are determined by their loudness; i.e., the strength of their “non-silence” energy. The active talker feature sums the 3 most active talkers in a conference, so that the conversation doesn’t get drowned out when too many people talk at once. The active talker feature also provides data on active talkers through the **dcb\_gettalkers()** and **dcb\_GetAtiBitsEx()** functions. These functions can be used by an application program to identify active talkers; for example, to provide a visual display highlighting the active talkers in a conference. The **dcb\_GetAtiBitsEx()** function returns the active talkers for all conferences on a DSP, while the **dcb\_gettalkers()** function returns the active talkers along with their party attributes for a specific conference.

The active talker feature is enabled by default and cannot be disabled. Active talker *notification* provides data on active talkers through the **dcb\_GetAtiBitsEx()** and **dcb\_gettalkers()** functions. You can enable or disable active talker notification (or identification) by using the **dcb\_setbrdparm()** function with the MSG\_ACTID parameter set to ACTID\_ON or ACTID\_OFF. This parameter does not enable or disable the active talker *feature*, which is always enabled. It only disables the *notification* to the application program.

- Notes:**
1. In some cases, it is desirable to inactivate the active talker feature, such as for a background music application program. Although you cannot directly disable the active talker *feature*, you can set the noise level threshold by which signals are recognized as either speech or noise. For more information on implementing background music, see [Chapter 10, “Background Music”](#).
  2. The active talker feature does not span conference bridges; that is, there is no active talker summing across conference bridges and active talkers are reported separately for each conference.

The **dcb\_gettalkers()** and **dcb\_GetAtiBitsEx()** functions provide a snapshot of the active talkers at a given moment. By default, the snapshot is updated every second. To change this value and specify how frequently the active talker status is updated, use the **dcb\_setbrdparm()** function with the MSG\_ACTTALKERNOTIFYINTERVAL board-level parameter and specify a value in 10 ms units. If a low value is used, it can affect system performance due to the more frequent updating of the status (which results in a high quantity of internal notification messages). If a high value is used, it will result in less frequent updating on active talkers, but the non-silence energy by a conferee may not be reported if it occurs between notification updates. For example, if the notification interval is set to 2 seconds and a conferee only says “yes” or “no” quickly in between notifications, that vocalization by the conferee will not be reported.

***Active Talker***

This chapter provides information about bridging multiple conferences together. The following sections are included:

- [Conference Bridging Overview](#) . . . . . 31
- [Conference Bridging Limitations](#) . . . . . 32

## 8.1 Conference Bridging Overview

Conference bridging allows the parties from separate conferences to speak with and/or listen to one another. Two or more conferences can be bridged together with this feature.

Conference bridging can be used to effectively expand a conference beyond the maximum size allowed by your particular configuration (see [Section 6.4, “Resource Allocation”](#), on page 27). Before a conference reaches its maximum size, create a second (master) conference and then connect the two conferences via a bridge.

The conference bridging feature uses the **dcb\_CreateBridge()** and **dcb\_DeleteBridge()** functions. These two functions allow for a bridge party to be created and deleted in the two separate conferences. The **dcb\_CreateBridge()** function translates to adding a full duplex party on each conference. The bridge parties have no attributes (NULL) and simply act as conduits between the two conferences.

The conference bridging feature uses TS\_BRIDGECDT data structure to provide information about the conference bridge. This structure is composed of three elements; two MS\_CDT structures and an unsigned integer. The two MS\_CDT structures are filled by the library as part of the **dcb\_CreateBridge()** function and returned back to the application. The unsigned integer provides the application with a unique bridge identification number.

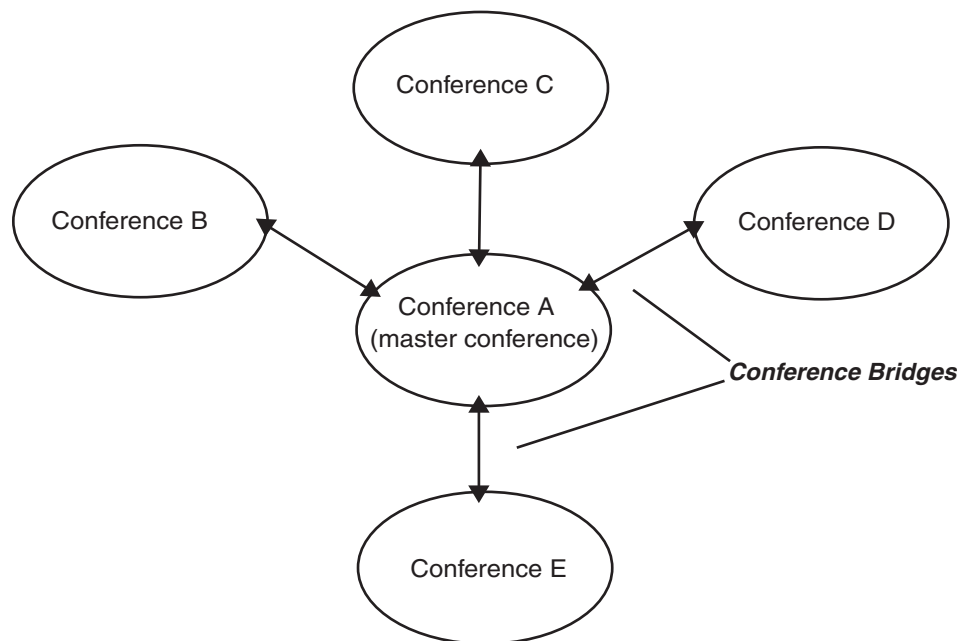
The MS\_CDT data structures of the bridged conferences are returned as part of the TS\_BRIDGECDT data structure. This structure makes it easy for application to track information about the conferences.

**Note:** Even though two (or more) conferences can be bridged together, the attributes and settings of each conference remain unchanged. The application is responsible for managing each conference and conference related events separately.

The conference bridging feature is implemented using a star configuration. The **dcb\_CreateBridge()** function designates a conference as the master conference and then adds all other conferences to the master conference as though they were individual NULL conferees.

For example, to connect five separate conferences (Conference A, Conference B, Conference C, Conference D and Conference E) you would have to invoke the **dcb\_CreateBridge()** conference four times, adding a different conference to the master conference (Conference A) each time. Figure 1 shows the star configuration of the conference bridging feature.

Figure 1. Star Configuration for Conference Bridging



## 8.2 Conference Bridging Limitations

The following limitations must be considered when using the conference bridging feature:

- Each bridge that is created consumes one conferencing resource in the master conference and one conference resource in the conference that is connected to the master conference.
- Conference bridges can span multiple DSPs and multiple conferencing boards. It is also possible to bridge together conferences that use the same DSP (by specifying the same device handle for the **hSrlDeviceA** and **hSrlDeviceB** parameters in the **dcb\_CreateBridge()** function).
- Conferences cannot be simultaneously bridged to multiple master conferences.
- You cannot bridge one master conference to another master conference.
- The coach/pupil feature does not span conference bridges. Coach and pupil must be in the same conference.
- The active talker feature does not span conference bridges; that is, there is no active talker summing across conference bridges and active talkers are reported separately for each conference.



This chapter provides information about controlling the volume for conferees.

- Output Volume Control ..... 33
- Input Volume Automatic Gain Control ..... 34
- Audio Input Muting ..... 34

## 9.1 Output Volume Control

This section provides information about adjusting output volume for individual conferees. Output (or speaker) volume refers to the volume that a conferee hears from the conference. A party in a conference may wish to change the volume level of the received signal, such as when the party is hearing impaired or the line has an excess amount of gain. Adjusting the output volume is accomplished using one of the following volume control features.

- User Control of Volume by Pre-Programmed DTMF Digits (Per Board)
- Direct Application Control of Volume (Per Party)

### 9.1.1 User Control of Volume by Pre-Programmed DTMF Digits (Per Board)

Use the `dcb_setbrdparm()` and `dcb_getbrdparm()` functions to set DTMF triggered volume control on a board basis. These functions use the `MS_VOL` data structure, which defines whether or not volume control is active for a conference and which DTMF digits increase, decrease and reset the volume.

The `MSG_VOLDIG` parameter in `dcb_setbrdparm()` allows the application to define the digits that cause the volume level to be adjusted up, down or back to the default value. When a conferee other than a monitor or receive-only party presses a digit programmed to change volume, the received signal is adjusted for that particular party only.

**Note:** The DTMF digits dedicated to volume control do not cause events to be sent to the application, even if digit detection is turned on using the `dcb_setdigitmsk()` function. Volume control digits are used only for controlling volume.

### 9.1.2 Direct Application Control of Volume (Per Party)

**Note:** This feature is **not** supported on Dialogic® Host Media Processing (HMP) Software.

Use the `dcb_SetPartyParm()` and `dcb_GetPartyParm()` functions to set volume control on an per-party or individual conferee basis with application-defined triggers. This method provides direct control to the application. You can set output volume to an absolute level by specifying `MSPA_OUTPUTVOLABS` for the party parameter, or you can set output volume to a level relative to the current level by specifying `MSPA_OUTPUTVOLRELCUR`.

## Volume Control

An application program can use this feature so that a conference moderator can adjust output volume levels for individual conferees, such as raising or lowering the volume for any conferee as needed. Also, by responding to user events (e.g., DTMF event), an application program could use this feature so that individual conferees may adjust their volume.

## 9.2 Input Volume Automatic Gain Control

*Note:* This feature is **not** supported on Dialogic® Host Media Processing (HMP) Software.

This section provides information on configuring automatic gain control (AGC) parameters for conferee input volume on a board basis. Input (or microphone) volume refers to the strength of the signal from the conferee's microphone.

AGC normalizes all conferee inputs to a target level. Although default AGC parameters are set at optimal levels, you can adjust AGC performance at the board level during board initialization. This is accomplished by changing the default values of the automatic gain control (AGC) parameters in the configuration file. The values that you enter will take effect on a board basis when the board is started.

The following AGC parameters can be configured. For details on these parameters, see the [0x3b] section of the Configuration Guide associated with your release. See also background information on AGC in the same document (e.g., the AGC algorithm is described in the “[Encoder] Section” of that document, which provides a figure on AGC Gain vs. Input Average).

- AGC K Constant: CSUMS\_AGC\_k\_Def (0x3B13)
- AGC Noise Level Lower Threshold: CSUMS\_AGC\_low\_threshold (0x3B1F)
  - Note:* Information on this parameter is also provided in [Chapter 10, “Background Music”](#).
- AGC Maximum Gain: CSUMS\_AGC\_max\_gain (0x3B1E)

## 9.3 Audio Input Muting

Muting and un-muting a party's audio input to a conference can be accomplished using the `dcb_setcde()` function and setting the following channel attributes in the MS\_CDT structure:

- MSPA\_MODERECVONLY - To mute a conferee
- MSPA\_MODEFULLDUPLX - To un-mute a conferee

*Note:* The attributes above cannot be ORed with any other conference attributes so that if other attributes are being set for a given conferee, `dcb_setcde()` must be called multiple times.

This chapter includes information about how to implement background music, such as for a dating chat line where two callers talk while music plays in the background.

**Note:** A media load specifically for background music is typically used with these types of applications to achieve the right mix of resources on the board and to maximize density. For Dialogic® Host Media Processing (HMP) Software, the desired ratio of resources is determined by the license.

Do the following to implement background music in a conference:

- Create a three-party conference, where one party is the music resource.
- When you add music to the conference, make the following parameter settings. Set its party attributes so that it uses transmit-only mode. That is, for the conference party that transmits music, enable the MSPA\_MODEXMITONLY attribute in the MS\_CDT data structure **chan\_attr** field.
- The Conferencing AGC Noise Level Lower Threshold may need to be adjusted. This parameter is set at -40 dBm by default and filters out any signals below this level. If the background music levels are low, the music may not be summed into the conference by the active talker feature, or it may come in and out. In this case, the AGC Noise Level Lower Threshold should be reduced by adding or changing the CSUMS\_AGC\_low\_threshold (0x3B1F) parameter in the configuration file for the board and re-starting the board. For more information on this parameter, see the Configuration Guide associated with your release.

## ***Background Music***

This chapter provides information on building applications using the Dialogic<sup>®</sup> Audio Conferencing API library. The following topics are discussed:

- [Compiling and Linking](#) ..... 37
- [Variables for Compiling and Linking](#) ..... 38

## 11.1 Compiling and Linking

The following topics discuss compiling and linking requirements:

- [Include Files](#)
- [Required Libraries](#)

### 11.1.1 Include Files

Function prototypes and symbolic defines are determined in include files, also known as header files. Applications that use audio conferencing library functions must contain statements for include files in this form, where <filename> represents the include file name:

```
#include <filename.h>
```

The following header files must be included in the application code **in the order shown** prior to calling the audio conferencing library functions:

*srllib.h*

Contains function prototypes and equates for the Dialogic<sup>®</sup> Standard Runtime Library.

*dtilib.h*

Contains function prototypes and symbolic defines for the Dialogic<sup>®</sup> Digital Network Interface library.

*msilib.h*

Contains function prototypes and symbolic defines for the Dialogic<sup>®</sup> Modular Station Interface library.

*dcplib.h*

Contains function prototypes and symbolic defines for the Dialogic<sup>®</sup> Audio Conferencing library.

### 11.1.2 Required Libraries

For Linux, you must link the following library files in the order shown when compiling your audio conferencing application:

*libsrlmt.so*

Standard Runtime Library file. Specify **-lsrl** in makefile.

*libdtimt.so*

Digital Network Interface library file. Specify **-ldti** in makefile.

For Windows<sup>®</sup>, you must link the following library files in the order shown when compiling your audio conferencing application:

*libsrlmt.lib*

Standard Runtime Library file.

*libdtimt.lib*

Digital Network Interface library file.

By default, the library files are located in the directory given by the INTEL\_DIALOGIC\_LIB environment variable.

**Note:** When compiling an application, you must list Dialogic<sup>®</sup> libraries first before all other libraries, such as operation system libraries.

## 11.2 Variables for Compiling and Linking

The following variables provide a standardized way of referencing the directories that contain header files and shared objects:

INTEL\_DIALOGIC\_INC

Variable that points to the directory where header files are stored.

INTEL\_DIALOGIC\_LIB

Variable that points to the directory where shared library files are stored.

These variables are automatically set at login and should be used in compiling and linking commands. The following is an example of a compiling and linking command that uses these variables:

```
cc -I${INTEL_DIALOGIC_INC} -o myapp myapp.c -L${INTEL_DIALOGIC_LIB} -lgc
```

**Note:** It is recommended that developers begin using these variables when compiling and linking applications since they will be required in future releases. The name of the variables will remain constant, but the values may change in future releases.

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